



ENGINEER
NEXT
NIDays

The logo is centered on a blue background with diagonal stripes. It features the words "ENGINEER" and "NEXT" in a large, white, sans-serif font, stacked vertically. A yellow graphic element, resembling a stylized 'X' or a folded ribbon, is positioned between the two words. Below "NEXT" is a white rectangular box containing the text "NIDays" in a smaller, white, sans-serif font. The entire logo is tilted at an angle, matching the background stripes.

Sparking Innovation in the Classroom With Mechatronics and the IoT

Mission Statement



NI equips engineers and scientists with systems that accelerate productivity, innovation, and discovery.

Grand Engineering Challenges



Advance
Personalized Learning



Make Solar
Energy Economical



Advance
Health Informatics



Enhance
Virtual Reality



Reverse-Engineer
the Brain



Engineer
Better Medicines



Provide Access
to Clean Water



Develop Carbon
Sequestration Methods



Restore and Improve
Urban Infrastructure



Secure
Cyberspace



Manage the
Nitrogen Cycle



Provide Energy
From Fusion



Prevent Nuclear
Terror

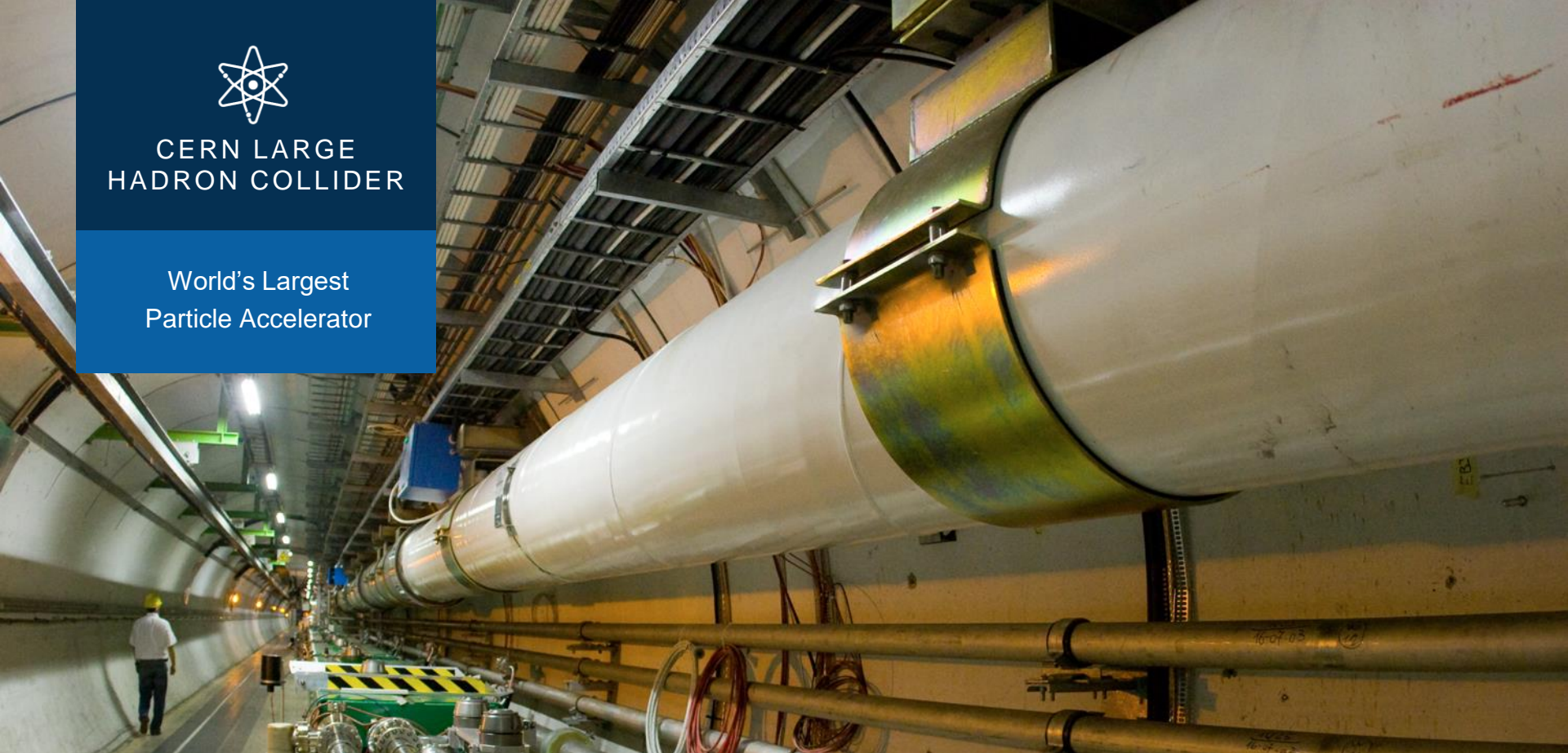


Engineer the Tools
of Scientific Discovery



CERN LARGE
HADRON COLLIDER

World's Largest
Particle Accelerator

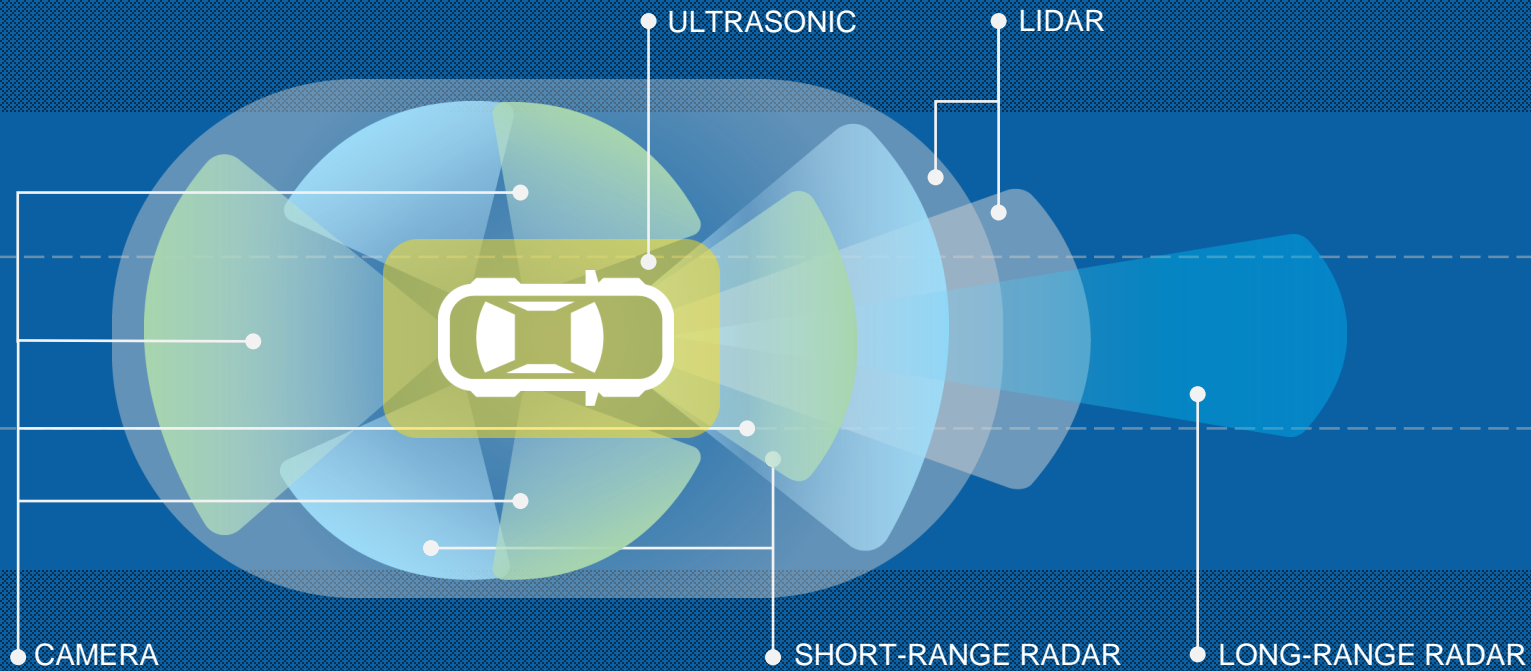


IEEE Spectrum

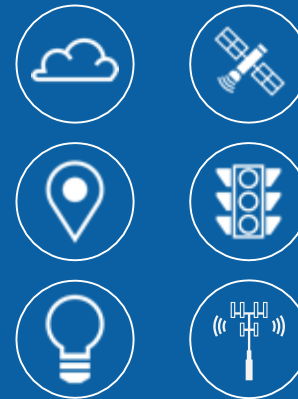
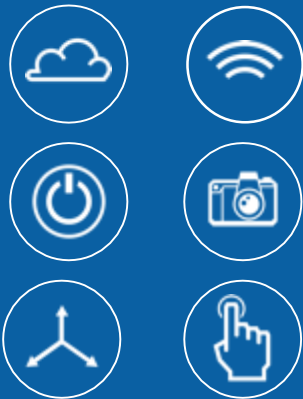
2020 will be the year when
5G Goes from Theory to Reality



Autonomous Vehicle



Student Focus Is on Engineering Systems



Student Focus Is on Engineering Systems



More capability defined in software

Functions change rapidly

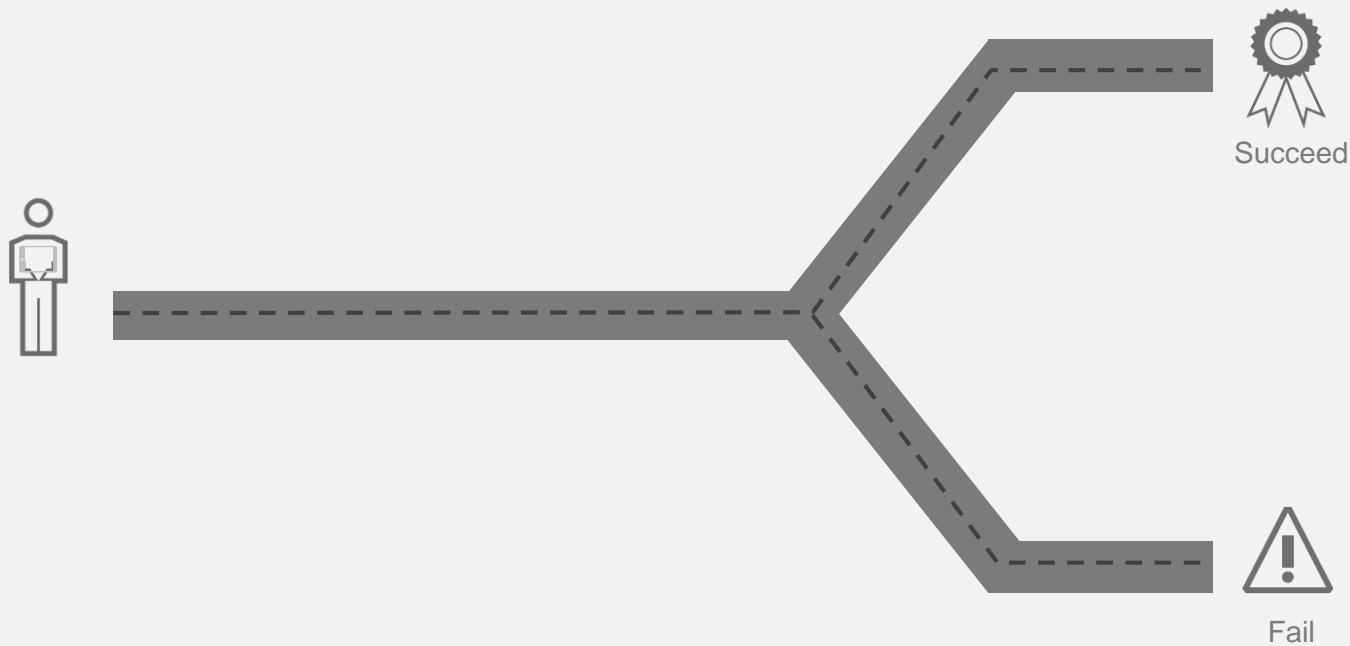
Increasingly complex to design and test

How Do We Prepare Students for Engineering System Design?

A blue-tinted photograph of an engineering laboratory. In the foreground, a man and a woman are looking at a computer monitor. The desk is cluttered with various electronic equipment, including a power supply unit, a breadboard with components, and numerous connecting wires. In the background, another person is visible working at a separate workstation. The overall scene depicts a collaborative engineering environment.

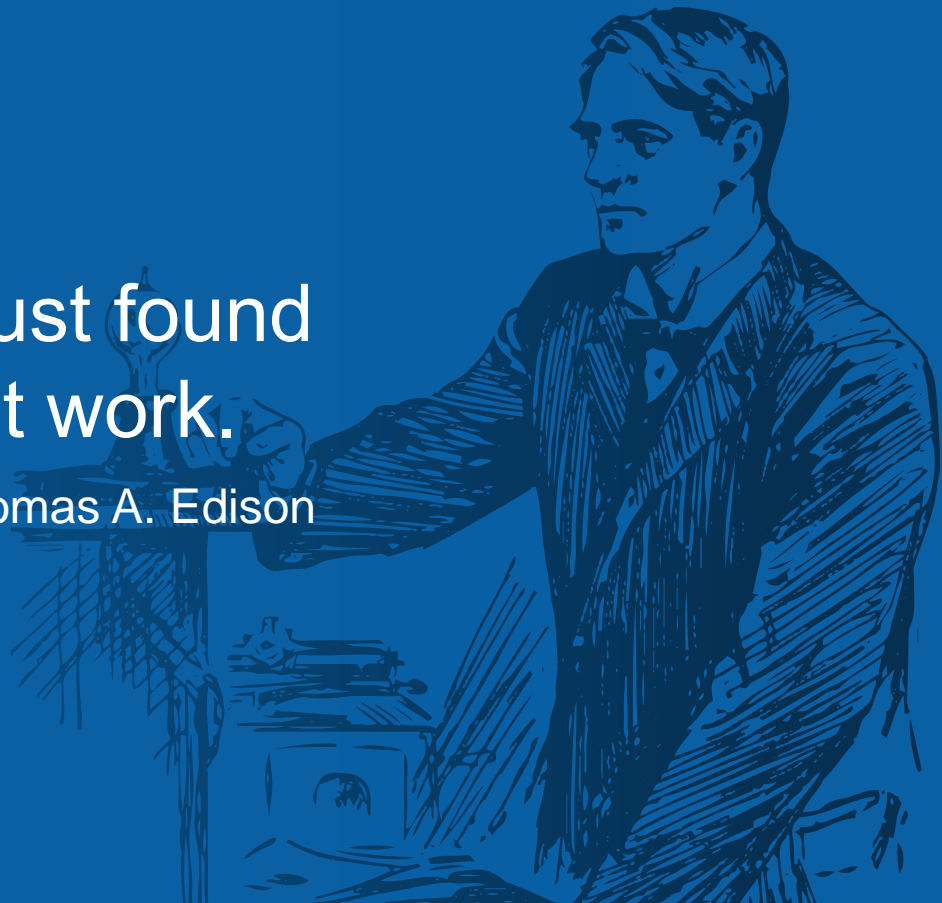
To Accelerate Engineering System Design,
the Rate of Discovery Matters

A Common Misconception

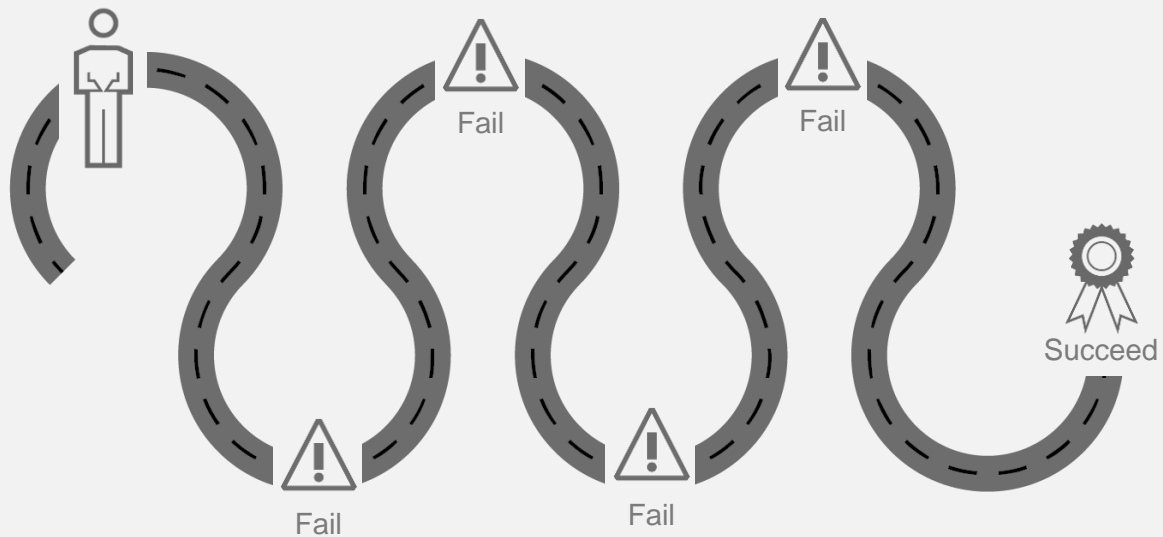


I have not failed. I've just found
10,000 ways that won't work.

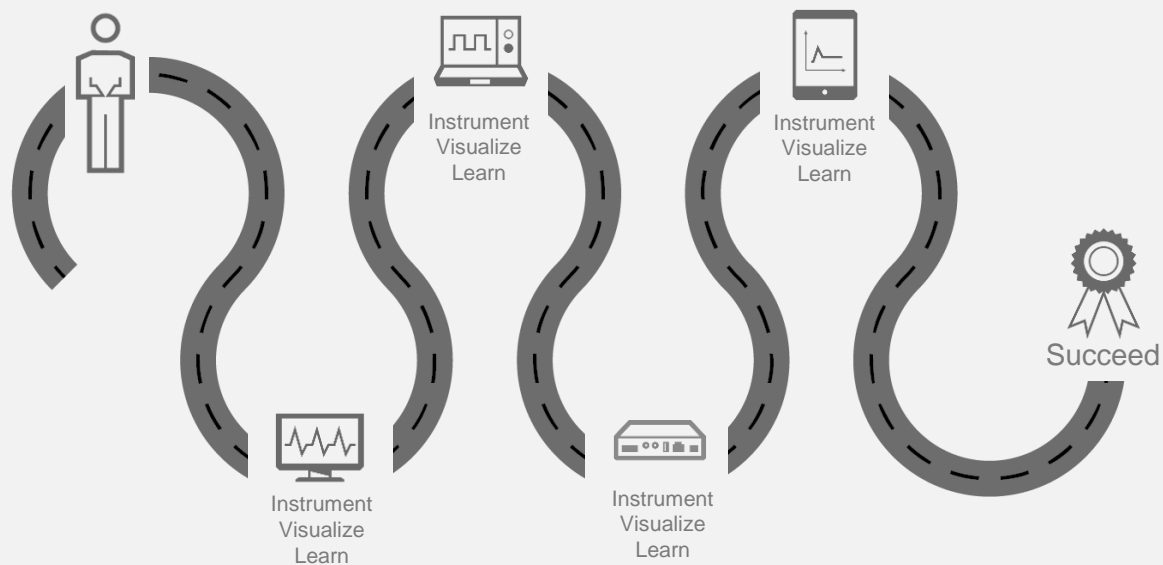
—Thomas A. Edison



True Path to Success



True Path to Discovery

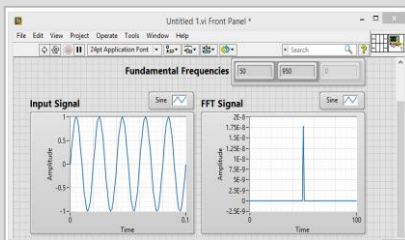


Accelerating Engineering System Design

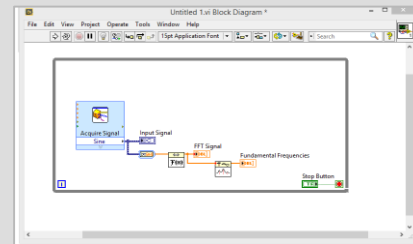
Rapid assembly of system
through modular I/O



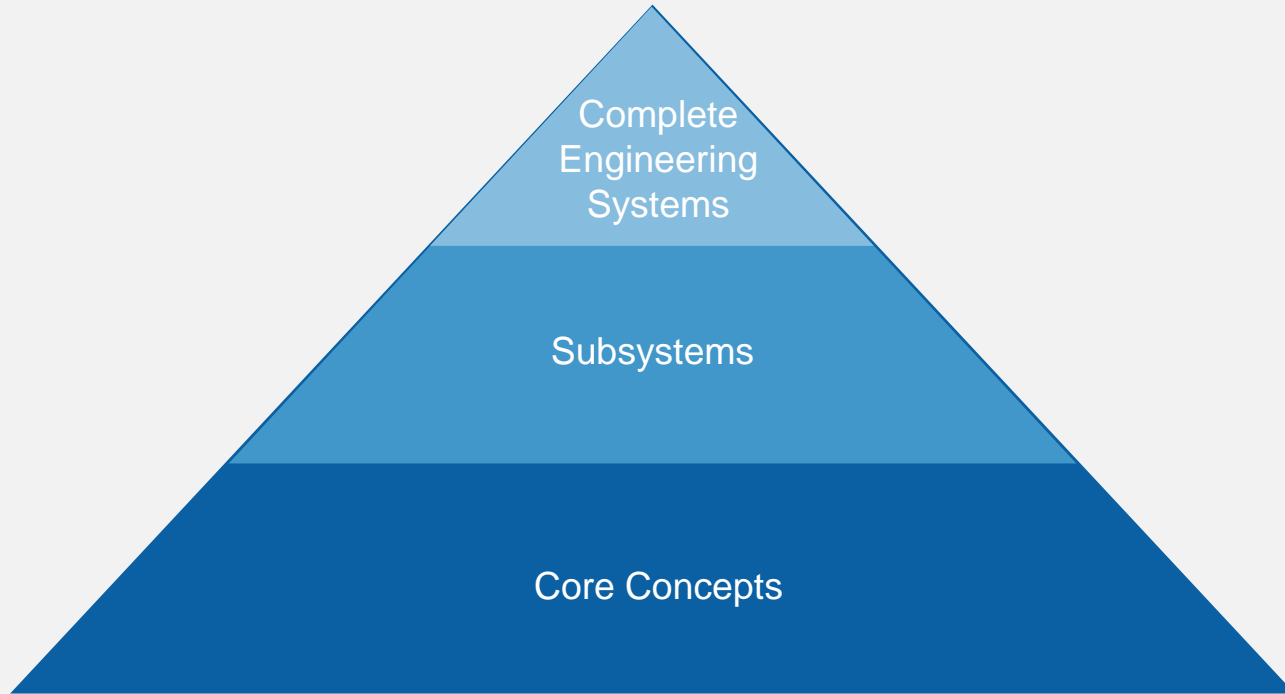
Instant insight at every step
through virtual instrumentation



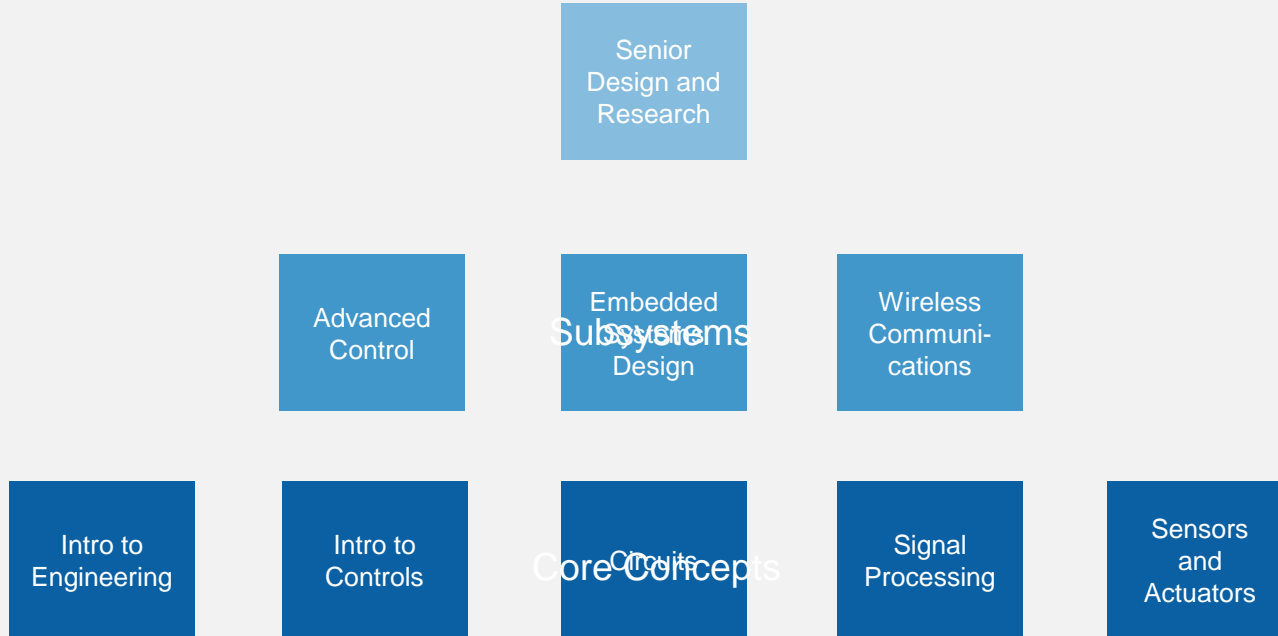
Software at a schematic-level
overview to integrate system



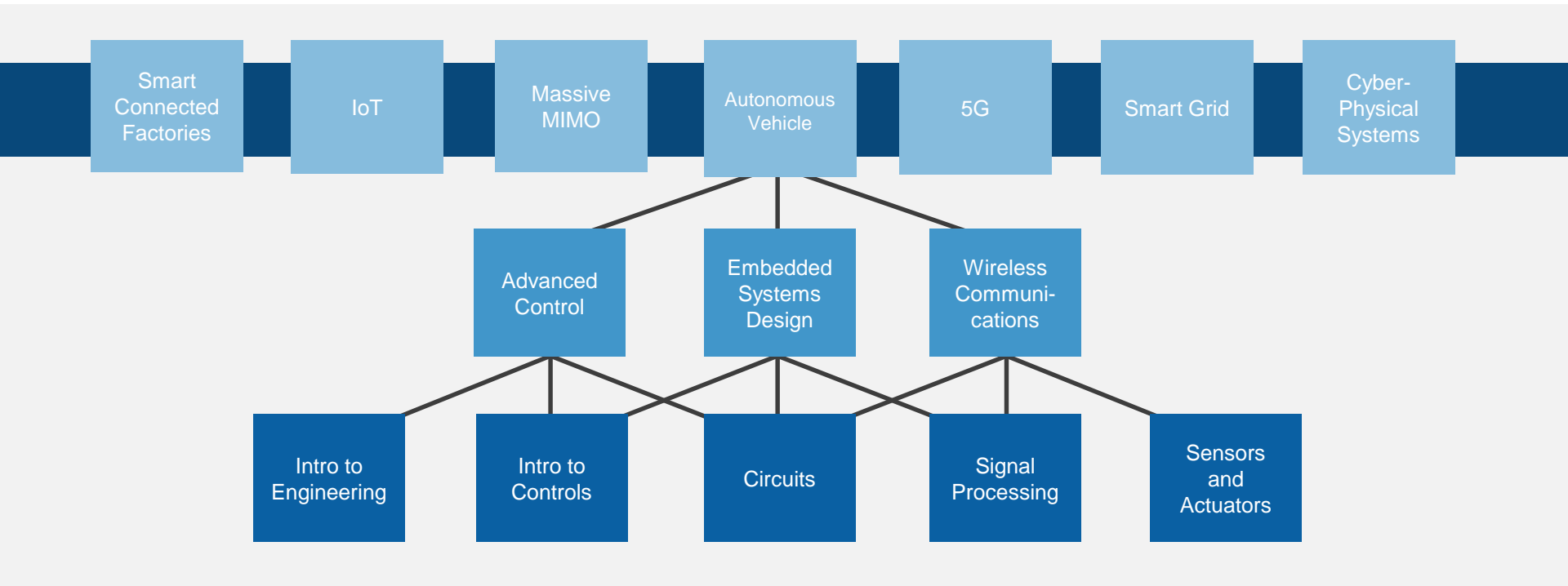
Path to Engineering System Design



Path to Engineering System Design



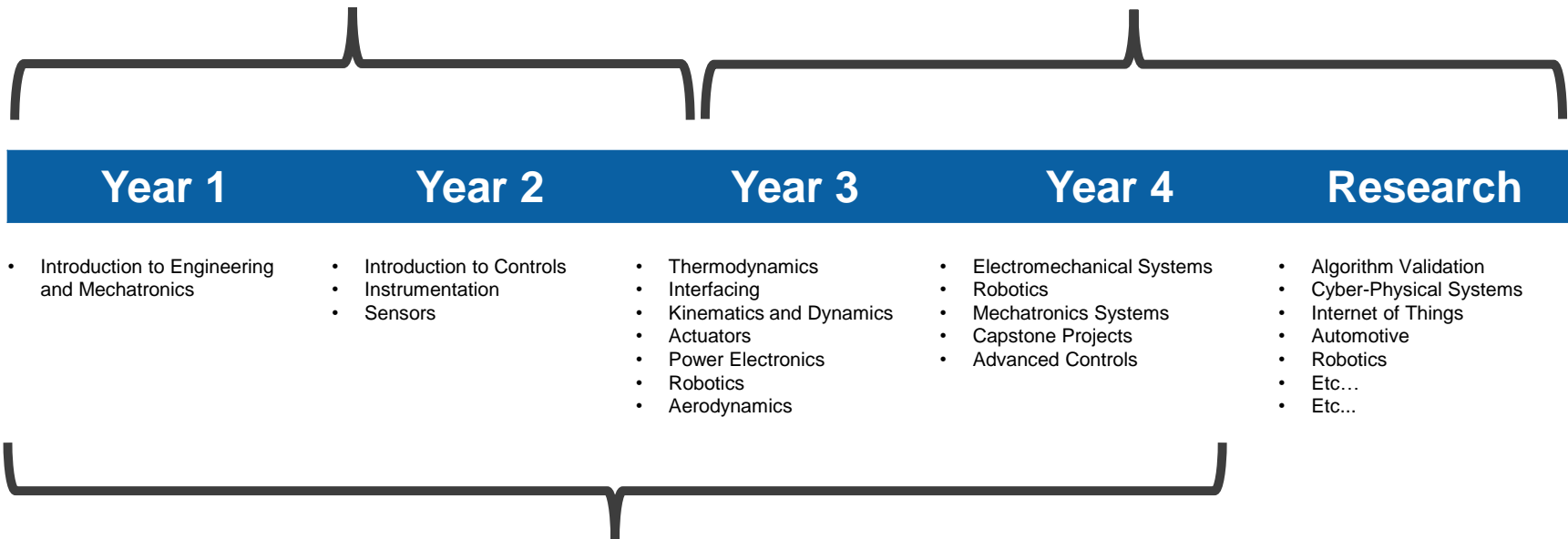
Path to Engineering System Design



Focus on Key Courses for Controls and Mechatronics

Foundational concepts

Subsystems and multidisciplinary systems



Broad set of topics with a focus on
instrumentation, controls, and mechatronics

Challenges in Accelerating Controls and Mechatronics Education

- Students excited by ambitious projects; less excited by foundational topics
- Limited laboratory time to build true understanding
- Differences in theory from laboratory results drive student confusion
- Students do not retain understanding of foundational concepts, which leads to difficulties in later multidisciplinary classes

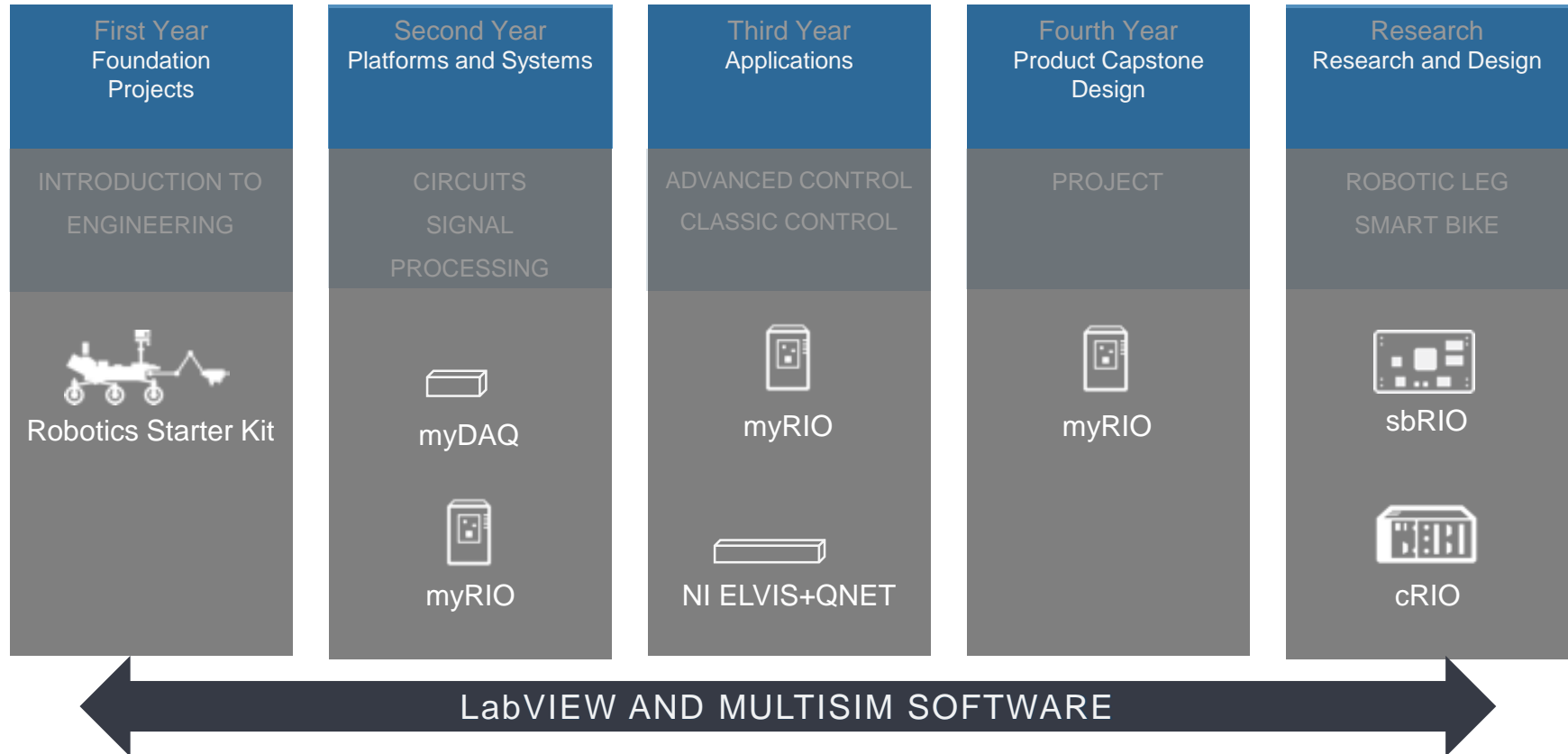
Tsinghua University

Success Story

- No. 1 ranked engineering program in the world (*US News*)
- Advanced controls and mechatronics topics taught in **Automation Program**
- Challenged to rapidly build student understanding of engineering topics toward outcome of complex design
- Students spent more time learning “new tools” each semester rather than focusing on engineering
- Built program on foundation of LabVIEW and Multisim software along with myRIO and NI ELVIS
- Program improved student engagement and employability and advanced robotics capstone projects



Tsinghua University



First Year
Foundation
Projects

High-Level
Abstraction



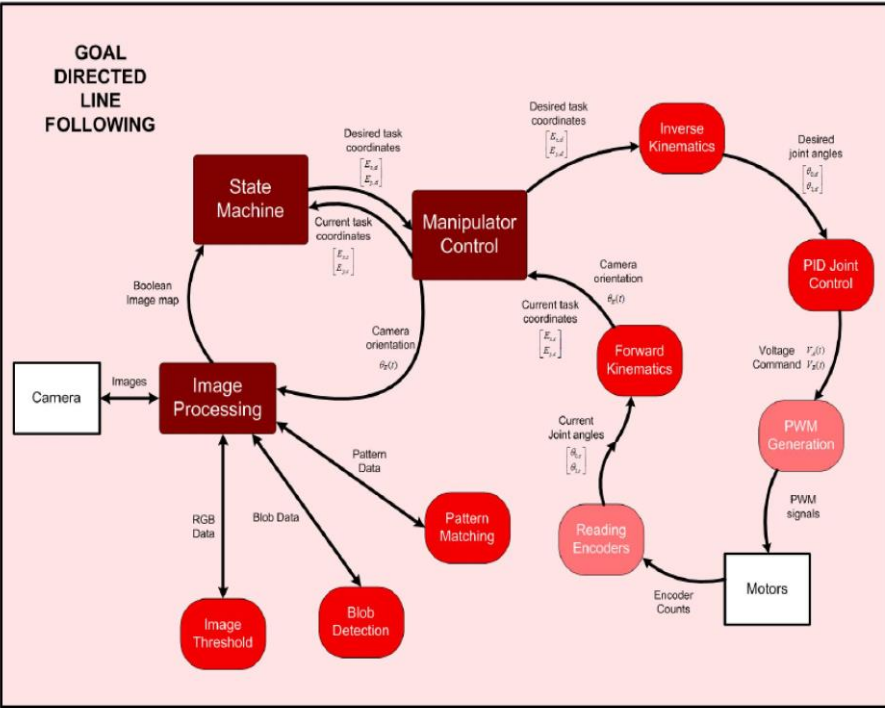
Mechatronic
Systems



Challenge: Goal-Directed Line Follower

- Create a vision algorithm that centers on a line that will represent a road
- Create a control algorithm that uses the feedback from the vision application you created to make setpoints for a manipulator arm to achieve
- Create a user input mechanism that allows for new paths to be provided as the system is following already-created paths

GOAL DIRECTED LINE FOLLOWING



First Year Goal-Directed Line Following

Vision
Control
Component Integration

PID
Inverse/Forward Kinematics
Path Planning
Blob Detection

